

Last Time

- practical UQ methods
- conformal prediction

Lecture 11

EAS S 25

ANDREA BAJCSY

This Time:

- "system-level" UQ / anomalies

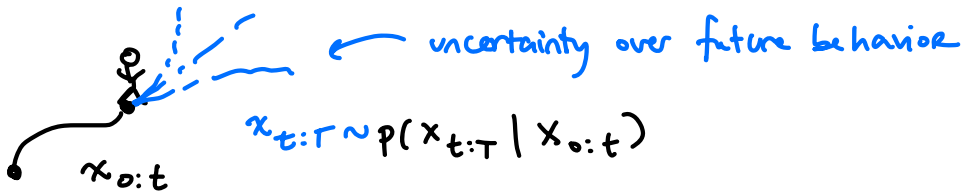
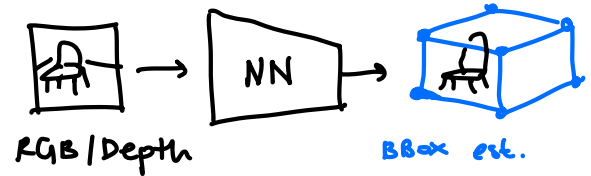
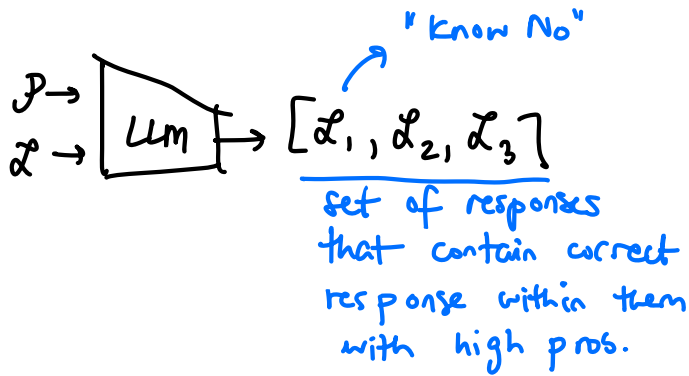
Announcement: HW #3 due April 2nd

"System-level" Uncertainty / Anomalies

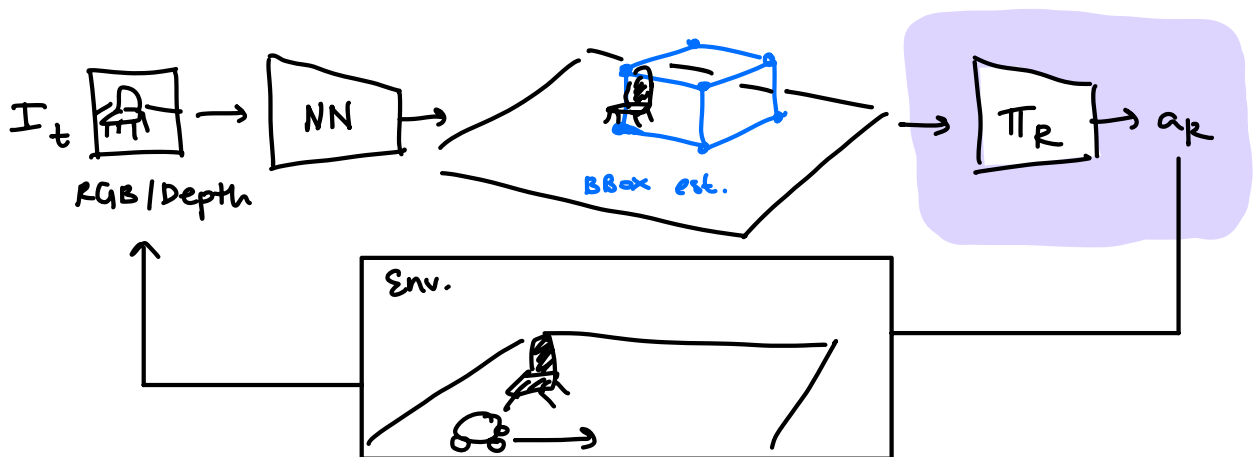
"prediction confidence"

"input / data uncertainty"

So far, we have been talking about SINGLE data-driven components of an autonomy "stack" and how to model their uncertainty



BUT, all these models "live" within the broader robotics pipeline; together influence the robot's next decision; thus, long-term outcomes.



System-level Uncertainty

- 1) consider the impact of the uncertainty (or anomalous data) on the downstream decision-making
- 2) use components throughout the autonomy stack to mitigate negative consequences.